

What is a Remote Controlled Acoustic Hailing Device?

Eltem's unique and innovative technology allows operators to observe the situation on the spot remotely even during day and night and also clear command and highly effective warning broadcasts to be transmitted to long distances (1~3km). It consists of a high powered Long Range Acoustic Hailing Device that is connected to the equipment via Ethernet and controls all functions remotely using dedicated control software, a motor that can be adjusted vertically and horizontally, a daytime camera and a thermal camera.



FEATURES

- Simultaneous Surveillance and Warning Broadcasting
- Superior Voice Intelligibility and Highly Clear Communication up to 1km
- High output of 142dB, 1km broadcasting distance (80dB standard)
- Network sound source and microphone broadcasting
- 360° (left and right) rotation, 180° (up and down) rotation
- 32x optical zoom camera
- Network control
- All-weather use
- Thermal camera (option)
- Searchlight (option)

Operation Concepts & System Components



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PROPA-250R SPECIPICATIONS

Communications Range	≥1000m (80dB)		
Maximum Output	142dB SPL @1m (Maximum output limit function according to the user requirement)		
Directivity	≤±15° (2kHz, -3dB)		
Dimensions	880× 386× 321mm, 880× 386× 528mm (included a search light)		
Weight	49kg, 52kg (included a search light)		
	Range	-90° ~ +90°	
Tilt	Speed	30°/s	
	Resolution	0.01°	
Pan	Range	360° (continuous rotation)	
	Speed	40°/s	
	Resolution	0.01°	
Camera	32x Optical Zoom, 1920×1080 pixel, 30 frame/sec		
Thermal Camera (Option)	100mm Optical Zoom, 640×480 pixel, 9 frame/sec		
Laser Pointer	Green Laser, 4W		
Communication Interface	TCP/IP, Acoustic broadcast, Remote Volume Control, Control Program		
Operating Temperature	-33°C ~ +60°C		
Storage Temperature	-40°C ~ +70°C		

Sound Pressure Level vs Distance



– 30~50dB	Quiet library, noise in the woods, bedroom
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- *50~60dB* General office noise
- 60~70dB Noise on large ship deck
- 70~90dB Small ship engine noise (above deck)
- *80~100dB* Noisy construction site, road noise
- 120~130dB Jet noise (100m)
- 130dB Above, we started to feel pain
- 160dB Rocket firing noise

Theoretically, we can hear sounds at 88dB at 500m, 82dB at 1km and 68dB at 5km.



Day Camera

SPECIPICATIONS



Image Device	1/2.8" 2.38M CMOS
Total/Effective Pixel	1,952(H) × 1,116(V), 2.18M 1,944(H) × 1,104(V) , 2.14M
Focal Length (Zoom Ratio)	4.44 ~ 142.6mm (Optical 32x)
Angular Field of View	H : 62.8°(Wide) ~ 2.23°(Tele) V : 36.80°(Wide) ~ 1.26°(Tele)
Min. Illumination	Color : 0.3Lux (1/30sec, F1.6, 50IRE) B/W : 0.03Lux (1/30sec, F1.6, 50IRE)
Focus Control	Auto / Manual / One push
Video Compression Format	H.264 (MPEG-4 part 10/AVC), MJPEG
Resolution	1920 x 1080, 1280 x 1024, 1280 x 960, 1280 x 720, 1024 x 768, 800 x 600, 800 x 450, 720 x 576, 640 x 480, 640 x 360, 320 x 240, 320 x 180

Thermal Camera (Option)



SPECIPICATIONS

Detector	Uncooled micro bolometer FPA
Resolution	640(H) x 480(V)
Pitch Size	17µm
Spectral Range	8~14µm
Thermal Sensitivity	< 0.05°C(50mK), F/1.0
Zoom Lens	100mm
Frame rate	<30Hz

DRI Range

Object	Conditions	Distances(m)	Object	Conditions	Distances(m)	<u>T</u>		
	Detection	2,450		Detection	6,000	Diefrestern 1 & 2		8 9
Human	R ecognition	650	Vehicle	R ecognition	1,750		Star Barris Contractor	
	Identification	330		Identification	900	and the start		oxil pending
						Detection	Recognition	Identificatio

DRI Definition

- Johnson Criteria
- Detection : ability to distinguish an object from the background(1±0.25 line pairs OR 2±0.5 pixels)
- Recognition : ability to classify the object class (animal, human, vehicle, boat ...) (4 ± 0.8 line pairs OR 8 ± 1.6 pixels)
 Identification: ability to describe the object in details (a man with a hat, a deer, a Jeep ...) (6.4± 1.5 line pairs OR 13 ± 3 pixels)
- A line pair is defined as one white line adjacent to a black line.
- <u>https://www.hgh-infrared.com/FAQ/Perimeter-Security/Definition-of-DRI-Detection-Recognition-Identification-ranges</u>



Laser Pointer or Dazzler

- 532nm Wavelength Green Laser
- Optical Power for Laser Pointer
 5mW / 50mW
 - Effective Distance : 1~2km
- Dazzler
 - 500mW
 - Effective Distance : 2~3km



• 5mW / 50mW Laser Pointer



❶ 500mW Laser Pointer



Laser Pointer



Laser Dazzler

- NOHD(Nominal Ocular Hazard Distance)
 - It specifies the distance from the laser source at which the intensity of a single laser beam becomes safe by not exceeding the MPE (Maximum Permissible Exposure) any more.
- NOHD is calculated at this site : <u>https://www.laserworld.com</u>
- NOHD as Power
 - Divergence : 1.2mrad, Diameter at aperture : 3mm

Item	Optical Laser Power	Distances(m)	
Lacar Daintar	5mW	11	
Laser Pointer	50mW	39	
Dazzler	500mW	129	



Searchlight(Option)

 Two Searchlights(360W) are mounted on PROPA-250R.





LED	LED 10W(12EA)
Size	180 x 207 x 92mm
Divergence Angle	15°
Power Consumption	120W
Power	DC 12~60V
Brightness	10000LUMEN
LED Color	White
Water Proof	IP67



• The beam of a searchlight is arrived to about 1km



Console with Control Program



CONSOLE LAYOUTS AND SPECIFICATIONS

Control Panel

- Joystick for PTZ
- Thermal Power on button
- Laser Pointer on button
- Main Window exchange button
- Motor Speed Control
- Audio File Play/Stop/FWD/FWD
- Toggle Microphone
- Amp Power and Volume Control
- Monitor 17.3inch TFT-LCD
- Resolution : 1920x1080
- Brightness : 400 cd/m²
- CPU Intel 6th Gen i5(2.4GHz)
- 8GB RAM
- SSD 128GB



External Connection Layouts

 Can connect external audio devices (MP3 Player, Wireless Microphone etc.) to the back panel of console.

Control Program

- Video Recording and Image Saving
- Display of the video of day camera and thermal camera simultaneously
- PTZ control with motor speed control
- Playback and Stop audio files, voice sound out with a toggle microphone
- Laser Pointer Power ON/OFF

Interfaced with ECDIS/Rader

- Receiving the objects information from ECDI (Electronic Chart Display and Information System) Radar through Serial Interface or TCP/IP.
- Display of the objects on the circular coordinate.
- If selects an object, Pan/Tilt is moved automatically.





Extern Audio Device





Display of the objects



Environment Certifications

- Random Vibration : MIL-STD 810F, Method 514.4
- Shipboard Vibration : MIL-STD-167-1A
- Shipboard Shock : MIL-STD-910D, Class I
- Shock : MIL-STD-810F
- High Temperature Operation : MIL-STD-810F, Method 501.4
- Low Temperature Operation : MIL-STD-810F, Method 502.4
- Operating Humidity : MIL-STD-810F, Method 507.4
- Salt Fog : MIL-STD-810F, Method 509.4
- Safety Standard : MIL-STD-1474D
- EMC Standard : FCC Part 15 Class A Radiated and Conducted Emissions
- Water and Dust Protection : IP66

Main Features of Acoustic Hailing Device

- Since it broadcasts with directivity and high power, it can transmit highly clear sounds to a long distant (1 km).
- With maximum output above 142dB, it can get over the noise of the surrounding areas and can provide highly intelligible and clear communication and warning signals to the inside of vehicles, ships or buildings, overcoming the limitation of the existing broadcasting system (P.A. System).
- It is possible to broadcast using sound sources and a microphone.





General Loudspeaker



PROPA-250R Remote Controlled Acoustic Hailing Device

Applications of Acoustic Hailing Devices



Emergency Warning & Fire Rescue

Fire Evacuation Broadcast, Public Place Guide and Evacuation Broadcast, Valley Evacuation Broadcast due to heavy rain, and Coastal Accident Prevention & Evacuation Broadcast





Military, Maritime, Security & Protection Military Training control, Anti-Piracy, Major Facility Intruder Warning, Preserving Wildlife & Protecting Assets

Law Enforcement, Homeland & Border Security

Illegal Activity Warning, Beach Announcement, Access Control Broadcast, Crowd Control







Installation in Ships, Vehicles and Drones Mounting on Warships, Ships, Fire Trucks, Ambulances, Police Cars, Helicopters, Drones

Traffic Accident Broadcasting, Traffic Control

Traffic Control, Prevention of Secondary Accident, Traffic Accidents and Foggy Broadcast, Emergency Evacuation Broadcast.



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